Signatures of contextual interference in implicit sensorimotor adaptation

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Contextual interference refers to the phenomenon whereby a blocked practice schedule results in faster acquisition but poorer retention of new motor skills compared to a random practice schedule. While contextual interference has been observed under a broad range of tasks, it remains unclear if this effect generalizes to the implicit and automatic recalibration of an overlearned motor skill. To address this question, we compared blocked and random practice schedules in a visuomotor rotation task that isolates implicit adaptation. In experiment 1, we found robust signatures of contextual interference in implicit adaptation: compared to participants tested under a blocked training schedule, participants tested under a random training schedule exhibited a reduced rate of learning during the training phase but better retention during a subsequent no-feedback assessment phase. In experiment 2, we again observed an advantage in retention following random practice and showed that this result was not due to a change in context between the training and assessment phases (e.g. a blocked training schedule followed by a random assessment schedule). Taken together, these results indicate that contextual interference is not limited to the acquisition of new motor skills but also applies to the implicit adaptation of established motor skills.

1. Introduction

Contextual interference is a widely observed phenomena, in which motor skills are acquired faster but poorly retained following a blocked practice schedule compared to a randomized practice schedule [1,2]. The ubiquitous nature of contextual interference has come to inform sports instructors [3–5] and rehabilitation specialists [6] (also see: [7–9]). For example, Hal et al. [3] had baseball players practice hitting curve balls, fast balls and changeups. Participants who were trained on the three types of pitches one at a time (blocked practice) learned faster but retained less than players who practiced hitting the three types of pitches in a randomized order. Similarly, Jo et al. [6] showed that individuals post-stroke who practiced different compensatory feeding skills in a blocked manner learned faster but retained less than those who practiced the skills following a randomized schedule.

Two related hypotheses have been proposed to account for the effect of contextual interference: According to the ‘elaborative-strategy hypothesis’ [1], random practice encourages a learner to compare and evaluate strategies that may be relevant for different motor tasks (e.g. how does preparing for a fastball differ from preparing for a curve ball), and consequently, endows the learner with better contrastive knowledge than that afforded by blocked practice. While the cognitive demands of this exploratory process can produce interference during random practice and, thus, decelerate the rate of learning, randomized practice results in richer and more elaborate long-term motor memories [10,11]. Alternatively, the ‘forgetting-reconstruction hypothesis’ [12–14] centers on the idea that random practice results in forgetting between repetitions of the distinct strategies required for different actions (e.g. hitting a fastball or curveball), forcing the learner to continuously reconstruct their explicit strategy with each repetition. While the forgetting process...
will attenuate the rate of learning, the act of reconstruction will result in stronger long-term memories.

Both hypotheses highlight the relevance of strategy and effort during randomized practice that consequently establishes more robust motor memories. However, whether contextual interference also holds for the implicit, effortless and automatic recalibration of an already established motor skill is poorly understood. Consider a classic sensorimotor adaptation task in which a rotation is imposed between the position of visual feedback and the position of the participant’s actual movement. When the perturbation is salient, adaptive changes in behaviour have been shown to entail at least two learning processes: A rapid, strategic process to nullify the perturbation and a slow, automatic process that implicitly recalibrates the sensorimotor map (similar dissociations also apply to prism [15], force field [16] and split-belt [17] adaptation tasks). The methods used in previous studies examining contextual interference effects in sensorimotor adaptation tasks do not partition performance changes associated with these two processes [18–22]. As such, it remains an open question as to whether implicit adaptation is also subject to contextual interference.

To fill this gap, we used a novel visuomotor rotation task in which learning is limited to implicit adaptation (figure 1a) [23–27]. On each trial, the participant reached to one of three visual targets with feedback provided by a visual cursor. Importantly, the angular position of the cursor followed an invariant path, always offset from the target by a fixed angle (clamped). Thus, unlike standard visuomotor adaptation tasks, the angular position of the cursor was not contingent on the position of the hand. Despite being fully informed of the manipulation and instructed to always reach directly to the target, participants exhibit a gradual, subconscious shift in heading direction in the opposite direction of the cursor, the classic signature of implicit adaptation [24]. Underscoring the implicit nature of adaptation in response to clamped feedback, when explicitly probed, participants report that their hand was near the target throughout the task despite exhibiting shifts in heading angle greater than 20° [24].

To evaluate contextual interference, we manipulated the schedule of the three reach locations. For a blocked schedule, each of the three targets was tested successively in blocks of trials. For a random schedule, the three targets were interleaved across trials. If contextual interference arises from resource-dependent strategic processes such as decision-making and working memory [28–31], we should not observe contextual interference when adaptation is elicited by clamped feedback. Alternatively, contextual interference may also be manifest during the implicit recalibration of an established skill.

2. Methods
(a) Participants
Participants were recruited via two online crowdsourcing platforms: Prolific and Amazon Mechanical Turk. We restricted our recruitment to participants who live in the United States, had an approval rating greater than 95% and had completed at least 50 web-based experiments. Participants were excluded if they completed previous web-based reaching experiments sponsored by our laboratory.

A total of 360 participants were recruited, each of whom completed one experimental session (approx. 40 min); 198 participants identified as male, 146 as female and 16 as other. Age ranged between 18 and 70 years old (mean ± s.d.: 32.6 ± 10.7). There were 295 participants who completed the experiment with a computer mouse and 65 participants with a trackpad. We did not enforce any restrictions on device usage since, in a previous study, we found that this factor did not affect reaching behaviour and visuomotor adaptation [32].

(b) Apparatus
Participants completed the experiment by accessing a dynamic webpage created using a customized platform, OnPoint [32]. The task progression was controlled by JavaScript running locally in the participant’s web browser. A typical computer monitor has a sampling rate around 60 Hz, with little variation across computers [33]. The program automatically detected the parameters of the participant’s monitor and used this information to adjust the size and position of the stimuli. For our sample, the average monitor size was 20-inch with a screen resolution of 1641 pixel width × 940 pixel height. For ease of exposition, the stimuli parameters reported below are based on this average screen resolution.

(c) Reaching task
The participant performed reach-like movements by moving the computer cursor with either the trackpad or mouse. At the beginning of each trial, participants moved the cursor (0.4 cm in diameter) to the start location, an annulus (0.5 cm in diameter) with visual feedback only provided when the cursor was within 2 cm of the annulus. After maintaining the cursor in the start position for 500 ms, a blue circular target appeared (0.4 cm in diameter) at a radial distance of 8 cm from the start location. On each trial, the target could appear at one of three locations on an invisible virtual circle (30°: upper right quadrant; 150°: upper left quadrant; 270°: lower middle).

Participants were instructed to produce a fast movement, attempting to ‘slice’ through the target. On feedback trials, the cursor remained visible throughout the duration of the movement and remained fixed for 50 ms at the radial distance of the target when the movement amplitude reached 8 cm. If the movement time exceeded 500 ms or if the reaction time exceeded 2000 ms, the message, ‘too slow’ was displayed in red 20 pt. Times New Roman font at the center of the screen for 750 ms. After each movement, the target (and feedback message when displayed) were blanked, and the participant moved back to the start location to initiate the next trial.

(d) Feedback conditions
Feedback during the movement could take one of the following forms: Veridical feedback, no-feedback or rotated non-contingent ‘clamped’ feedback. During veridical feedback trials, the movement direction of the cursor was veridical with respect to the movement direction of the hand. That is, the cursor moved with their hand as would be expected for a normal computer cursor. During no-feedback trials, the cursor was extinguished as soon as the hand left the start annulus and remained off for the entire reach. During rotated clamped feedback trials, the cursor moved along a fixed trajectory relative to the position of the target (8 cm), a manipulation shown to isolate implicit motor adaptation [23,24]. The radial position of the feedback cursor was contingent on the participant’s movement, matching the radial distance of the hand from the start position. However, the angular position was not contingent on the movement, appearing at a fixed angular offset relative to the visual target. The fixed angular offset was either 30°, 45° or 60° (see below). The participant was instructed to ‘ignore the visual feedback
Figure 1. Contextual interference is observed in implicit sensorimotor adaptation. (a) Schematic of the clamped feedback task. The cursor feedback (black circle) follows a constant trajectory rotated relative to the target (Exp 1: 30°, 45°, and 60°; Exp 2: 45°), independent of the position of the participant’s hand. Participants were instructed to always move directly to the target (blue circle) and ignore the visual clamped feedback. Left, middle and right panels display hand and cursor positions during the early, late and aftereffect phases of adaptation, respectively. (b, e, h) Mean time courses of hand angle in each experiment. The blocked training group is shown in black, and the random training group is shown in orange. Shaded error bars denote SEM. (c, f, i) Retention as a function of training schedule. (d, g, j) Retention delineated by the order of targets during the training phase (d, g) or by the order of targets during the no-feedback assessment phase (j). Dashed orange line denotes the mean retention over all three targets for the random training group. These targets were interleaved, and therefore do not have a specific order. Box plots show minimum, median, maximum and 1st/3rd IQR. Dots denote individuals. *p < 0.05.
and reach directly to the target. See a video describing our task at [https://www.youtube.com/watch?v=wdv50wpbMFe](https://www.youtube.com/watch?v=wdv50wpbMFe).

(e) Experiment 1

One hundred and twenty participants were recruited via Amazon Mechanical Turk for experiment 1. Participants were randomly assigned to one of two groups: blocked train/random assess group and a random train/random assess group (60 per group). There were no significant differences in age between the two groups (mean ± s.d., random train/random assess: 26.35 ± 5.38; blocked train/random assess: 26.60 ± 5.52; t_{114} = 0.25, p = 0.80). Experiment 1 had 345 trials, divided into four phases (electronic supplementary material, table S1): a baseline no-feedback phase (15 trials, 5 reaches per target), a baseline veridical feedback phase (30 trials, 10 per target), a clamped feedback training phase (270 trials, 90 per target) and a no-feedback assessment phase (30 trials, 10 per target).

Prior to the baseline and assessment phases, an instruction screen was presented informing the participant to reach directly to the target. Prior to the clamped feedback training phase, an instruction screen informed the participant that the cursor would no longer be under their control. The instructions stated that the participant should ignore the visual feedback and reach directly to the target. Six demonstration trials were included to familiarize the participant with the visual clamped feedback. On these trials, the target appeared at 0° (right side of the screen), with clamped feedback provided at a 180° offset from the target. The instructions about the nature of the clamped feedback were repeated before each demonstration trial.

During the clamped feedback training phase, participants reached to one of three movement targets on each trial, separated by 120°, with a different clamped visual error size (30°, 45°, 60°) assigned to each target, counterbalanced across participants. Generalization of implicit adaptation is minimal among targets separated by more than 45° [23,34,35], as such, reaching movements to each target are independently recalibrated. Clamp size, clamp direction and target location pairings were fully counterbalanced across participants.

The key manipulation centered on the structure of the training phase. For the random train/random assess group, the target location was randomized within cycles of three trials (one/target location). For the blocked train/random assess group, the targets were presented in a blocked fashion: 90 trials with one target, followed by 90 trials with a second target, followed by 90 trials with the third target. The order of the targets was counterbalanced across participants in the blocked train/random assess group. Baseline and no-feedback assessment phases were identical for both groups, with the target order pseudo-randomized such that each target appeared once every three trials. Randomly interleaving the three targets in the no feedback assessment phase ensures that retention is assayed in the same way for both groups.

(f) Experiment 2

The aim of experiment 2 was to address a potential confound in experiment 1: the contextual change that occurs between the training and assessment phases. For the random training group, this change was limited to the removal of the visual feedback. For the blocked training group, there was also the change from making repeated reaches toward a single target to interleaved reaches toward different targets. The attenuated retention for the blocked group in experiment 1 (see Results) may reflect an effect of this contextual change.

To address this, we designed a 2 × 2 between-participant experiment involving 240 participants recruited via Prolific (randomly assigned; 60 per group), crossing training schedule (blocked versus random) with assessment schedule (blocked versus random). There were no significant differences in age across groups (mean ± s.d., random train/random assess: 38.32 ± 11.57; random train/blocked assess: 38.93 ± 11.91; blocked train/random assess: 40.52 ± 11.65; blocked train/blocked assess: 36.45 ± 10.45; F_{2,234} = 1.26, p = 0.29).

As in experiment 1, random assessment indicates that the three targets were interleaved during the no-feedback assessment phase. Blocked assessment indicates that the three targets were provided in a sequential manner. In the blocked train/blocked assess group, the last training target was always assessed first so that we could evaluate retention of the most recently trained target. In the random train/blocked assess group, there were no constraints on which target was assessed first since all three targets were recalibrated simultaneously. The order of the three targets during the assessment phase for this group was counterbalanced (see electronic supplementary material, table S1 for more details).

Experiment 2 had a total of 345 trials and an identical schedule as in experiment 1 (electronic supplementary material, table S1). Since the effects of clamp size had little impact on implicit adaptation and contextual interference effects in experiment 1 (electronic supplementary material, figure S1), we opted to use a single clamp size (45°) for each target location. The direction of the clamp (clockwise or counterclockwise) was counterbalanced across participants.

(g) Data analysis

The primary dependent variable was hand angle, defined as the angle of the hand relative to the target when the amplitude of the movement reached the target radius (8 cm). Positive hand angle values correspond to the direction opposite the rotated feedback (i.e. we flipped all hand angle values at targets where a counterclockwise rotation was provided). The data were averaged across cycles (three successive reaches), and baseline subtracted to aid visualization. Baseline was defined as mean hand angle over the last 5 movement cycles of the baseline phase with veridical feedback. To assess adaptation relative to idiosyncratic biases, the mean hand angle at each cycle was baseline corrected on an individual basis [36,37].

Outliers were defined as trials in which the hand angle deviated by more than three standard deviations from a moving 5-trial window, or if the hand angle on a single trial was greater than 90° from the target. These trials were discarded since behaviour on these trials likely reflects attentional lapses (average percentage of trials removed: experiment 1: 1.1 ± 0.7%; experiment 2: 1.4 ± 1.1%).

The degree of implicit adaptation was quantified as the change in hand angle in the opposite direction of the rotation. We calculated hand angle during early adaptation, late adaptation and the aftereffect phase. Early adaptation was defined as the mean hand angle over the first 10 movement cycles during the clamped feedback perturbation phase. Late adaptation was defined as the mean hand angle over the last 10 movement cycles during the clamped feedback perturbation phase. Aftereffect was operationalized as the mean hand angle over the first two movement cycles of the no-feedback assessment phase. Retention was quantified as the percentage of adaptation remaining after visual feedback was extinguished, that is the ratio between the aftereffect and late adaptation hand angle (i.e. retention ratio = aftereffect divided by late adaptation). Note that since contextual interference effects were largely similar across clamp sizes in experiment 1 (electronic supplementary material, figure S1), we collapsed across clamp size in the main analyses to focus on the effect of training schedule.

The hand angle and retention ratio data were evaluated using a linear mixed effects model (R function: lmer). The fixed and random effects are summarized in electronic supplementary material, table S2. *Post-hoc* pairwise statistical tests were performed using *t*-tests (R function emmeans). *p*-values were adjusted for
multiple comparisons using the Tukey method. Standard effect size measures are provided (Ω² for between-participant comparisons; ω² for between-subjects ANOVA) [38]. When assumptions of normality were violated, we used the robust linear mixed effects model (R function: lmer) and the Wilcoxon rank test (R function: wilcox.test), statistical methods shown to be robust to distributional assumptions [39].

3. Results

(a) Experiment 1

The adaptation functions for the random (orange) and the blocked (black) groups are shown in figure 1b. During the baseline phases, participants moved directly to the target. When the clamped feedback was introduced, both groups exhibited a gradual shift in heading direction, approaching an asymptote around 20°, a value convergent with that observed in previous studies that employed the clamped feedback method [23,40]. After visual feedback was extinguished, participants exhibited a pronounced aftereffect, a key signature of implicit sensorimotor adaptation. Since this aftereffect was of similar magnitude for all clamp sizes [40], these results are consistent with previous reports showing that implicit adaptation decays with time between training and assessment [41–43].

Given the effect of delay, we performed a stronger test of contextual interference by limiting the analysis to reaches to the third training target location for the blocked group, comparing retention for this target to the average retention for all random group. Strikingly, retention remained significantly larger in the random group (Wilcoxon-test: W = 2536, p < 0.001). Taken together, we observed marked signatures of contextual interference in implicit adaptation, even when the delay between training and assessment was equalized.

(b) Experiment 2

In addition to delay, there is a second confound in experiment 1: the contextual change that occurs in the test phase. For the random training group, this change was limited to the removal of the visual feedback. For the blocked training group, there was also the change from making repeated reaches toward a single target to reaches toward interleaved targets. The attenuated retention for the blocked group may reflect, at least in part, an effect of this contextual change. To address this concern and evaluate whether the assessment schedule would modulate contextual interference, we adopted a 2 × 2 between-subject design in experiment 2 (n = 240, 60 per group), crossing training schedule (random, blocked) with assessment schedule (random, blocked).

We first focus on performance during the perturbation phase. All four groups exhibited robust implicit adaptation (random assessment groups in figure 1c; blocked assessment groups in figure 1h). There was a main effect of phase, with implicit adaptation being greater late compared to the early (F_{1,247} = 261.3, p < 0.001, η_p² = 0.75). The main effect of assessment schedule was not significant (F_{1,452} = 0.4, p = 0.55, η_p² = 0.00), a result that provides a sanity check given that the assessment manipulation does not come into play until the no-feedback assessment phase (and this factor did not interact with the other variables during this phase).

The main effect of training schedule was not significant, suggesting that random and blocked training groups exhibited a similar degree of implicit adaptation. Importantly, there was a significant interaction between training schedule and phase (F_{1,247} = 12.4, p < 0.001, η_p² = 0.05): blocked training led to faster early adaptation compared to the random training (t_{461} = 2.8, p = 0.02, D = 0.7). Similar to experiment 1, the difference in early adaptation between groups diminished in late adaptation (t_{461} = 1.3, p = 0.20, D = 0.1). However, unlike experiment 1, we did not observe a significant reversal in learning (we return to this issue in section 3c below).
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ing group to retention for reaches only to the last training target

we compared retention for all three targets in the random train-

immediately after training): in the random assessment groups,

Indeed, retention decreased incrementally with assessment

target, and least retention for the 3rd assessed target).

order (figure 1)

Given the effect of delay, the strongest test of contextual

interference requires a comparison of conditions in which the

timing of the assessment is roughly equalized following

random or blocked training (i.e. targets that were assessed

immediately after training): in the random assessment groups,

we compared retention for all three targets in the random train-

ing group to retention for reaches only to the last training target

in the blocked training group. Correspondingly, in the blocked

assessment groups, the retention comparison between the two

training groups was limited to the first target assessed. Strik-

ingly, retention was greater following random training in

both scenarios (Wilcoxon test: blocked assess, \( W = 2607 \), \( p < 0.001 \); random assess, \( W = 2510 \), \( p < 0.001 \)). These results high-

light a robust contextual interference effect in implicit adap-

ation, one that holds across different assessment schedules.

(c) Pooling together data from all conditions

Taking advantage of the large behavioural dataset obtained

across these two online experiments (\( n = 360 \)), we pooled

the data to examine the overall effect of contextual interfer-

cence in implicit motor adaptation. As shown in figure 2, 

compared to blocked training, random training resulted in

attenuated early adaptation (figure 2a: \( t_{359} = 6.6, p < 0.001, 

D = 0.7 \)). By the end of the perturbation phase, adaptation is

numerically greater from random training, although there is

no statistical difference between the two types of training 

(figure 2b: \( t_{358} = 1.9, p = 0.06, D = 0.2 \)). Most striking is the

greater retention associated with random training: Even

when limiting the analysis to conditions in which adaptation 

was immediately assessed, random training resulted in a

17% increase in retention over blocked training (figure 2c: 

\( W = 22864 \), \( p < 0.001 \)).

4. Discussion

Contextual interference is a widely discussed phenomena in

the skill acquisition literature, with random practice sche-

dules resulting in slower acquisition but better retention than

blocked practice schedules. Here, we asked whether

contextual interference will also manifest during the implicit 

and automatic adaptation of an established motor skill, 

reaching. To test this, we employed a visuomotor adaptation 

task in which performance changes are solely due to

the operation of implicit processes [23,24,27,44,45]. In two

experiments, we found that participants who performed

interleaved reaches to three different target locations consist-

ently adapted at a slower rate but exhibited better retention. 

These effects persisted even when the schedule of assessment 

and the timing of assessment were tightly controlled. Taken

together, these results broaden the scope of contextual inter-

ference to encompass both the acquisition of new motor 

skills and the implicit recalibration of a highly learned skill.

Our findings do not fit easily into the ‘forgetting-recon-

struction’ and ‘elaborative-strategy’ accounts of contextual 

interference [1,12]. These two hypotheses have focused on 

how random training enhances cognitive control during 

motor skill acquisition. As a result, random training imposes 

greater interference during learning due to the presence of 

competing strategies, but at the same time, establishes more 

robust motor memories. However, it is highly unlikely that 

participants in the clamped feedback task use a re-aiming 

strategy to offset the visual error [46,47]. Not only do the

instructions emphasize that they should always aim directly 

to the target and ignore the visual cursor, but participants 

also report that their hand position remains near the target 

throughout the perturbation phase [24]. As such, the con-

textual interference effects elicited in the current studies does 

not arise from interference occurring during random training 

between competing (explicit re-aiming) strategies.

A more generic account of contextual interference effects 

centers on the difference in attentional demands for blocked 

and random training conditions [48,49]. Specifically, while

Figure 2. Comparing random and blocked training across all experimental conditions: (a) early adaptation, (b) late adaptation and (c) retention. Box plots show min, median, max and 1st/3rd IQR. * \( p < 0.05 \). Dots denote individuals (\( n = 360 \)). Outlier individuals greater than 1st/3rd IQR are not shown.
attention to the task is likely to be high near the start of the experiment, it is likely to dissipate as the task becomes familiar. By this hypothesis, the early benefit from blocked practice would come about because the high state of attention allows the system to rapidly come up with a solution. However, over time, blocked practice is likely to lose its attentional hold, leading to reduced retention relative to random practice. While this hypothesis can account for the current results, it is predicated on the assumption that the strength of implicit adaptation is modulated by attentional state. Although the effect of attention on adaptation has been the subject of many studies, this work has generally involved perturbations that engage both explicit and implicit learning processes [50–52]. Future work using methods that restrict learning to implicit processes [23,24] would be useful to assess an attentional account of contextual interference.

Another hypothesis of contextual interference in implicit adaptation may be derived from work suggesting that implicit adaptation entails multiple processes that operate at different time scales [53,54]. In a two-rate version of this model, one process adapts and decays quickly, operating in the seconds range (‘labile’, or ‘fast’ component), whereas a second process adapts and decays slowly, with the effects persistent across days (‘stable’, or ‘slow’ component) [41,55–57]. We assume that these processes operate in parallel yet are constrained to reach a fixed asymptote due to limits in motor or sensory plasticity [40,45]. As such, they trade-off: If implicit learning is dominated by the labile component, the stable contribution will be reduced. The relative contribution of labile and stable components will differ for blocked and random schedules. Blocked training, entailing repeated reaches to a single target, favours the accumulation of adaptation within the fast, labile process, resulting in fast adaptation but poor retention. By contrast, random training with relatively long temporal delays between reaches to a given target favours the slow, stable process with the labile component decaying between successive reaches to that target. This would result in slower adaptation yet better retention. Future studies can provide direct tests of this hypothesis, asking how contextual interference in implicit adaptation is impacted by the inter-trial interval between successive reaches. We would predict that the retention cost associated with blocked practice would be eliminated by extending the inter-trial interval.

References
